

ABSTRACT

Handling of each arrayed component is implemented in pickup operation within a movement range of a supporting body against the size of a supporting region of the arrayed component smaller than that in the prior art. Each component (2) supported on a supporting body (6) in array is moved to a pickup position (C) with a movement of the supporting body (6) in X and Y two component array directions, and is fed to pickup operation by a tool (3) with push-up operation by a push-up pin (8) involved, in which after each unit region (D1 to D4) dividedly set around the pickup position of the supporting body (6) is positioned at a pickup standby position (E) by rotation of the supporting body (6) in a switching manner, the component (2) in the positioned unit region is moved in each component array direction of the supporting body (6) and fed to pickup operation in sequence.

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